

Learning Reaction Barriers And Related Geometries

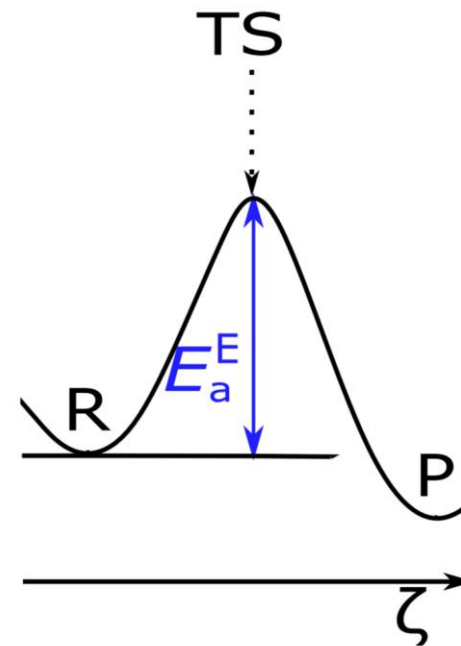
Guido Falk von Rudorff, University of Vienna

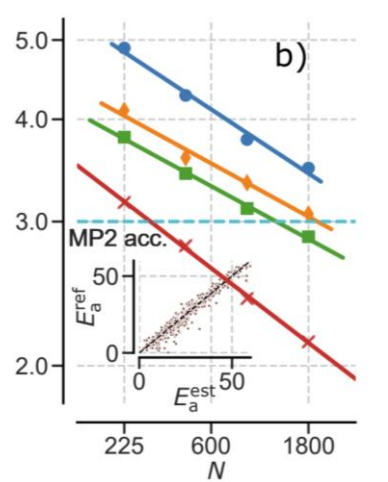
 ferchault

 @ferchault

 guido.vonrudorff.de

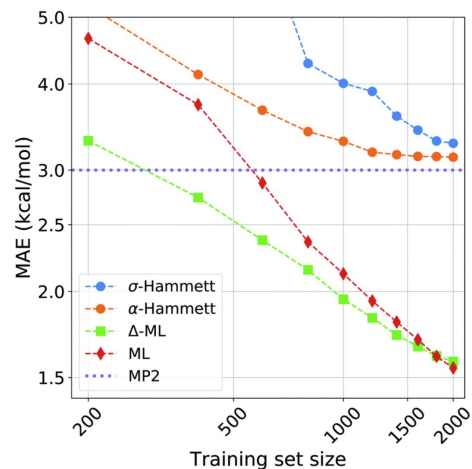
- Reactions: complicated landscape
- Not only expensive but also hard problem
- Even if the reaction mechanism is known:
 - Find reactant (R)/product (P) complexes
 - Find transition state (TS) geometries
 - Describe energy near TS
 - Low level of automation available
- Machine learning: accelerate & less supervised






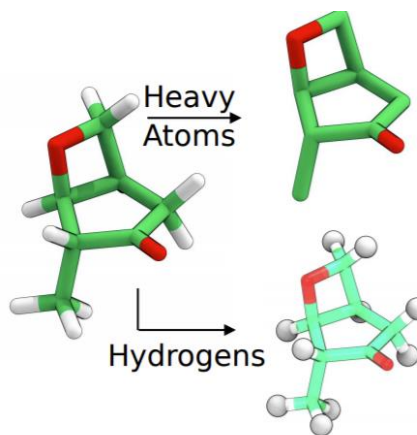
Energies with KRR

 [qmlcode/qml](https://github.com/qmlcode/qml)



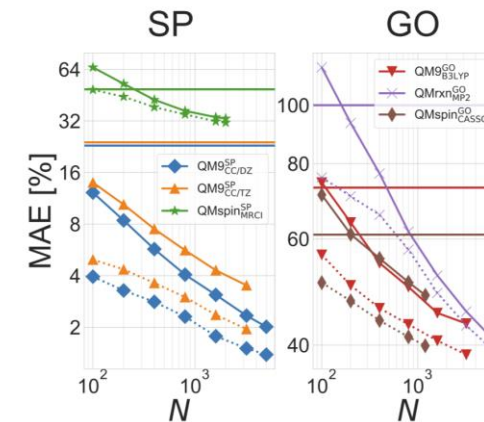
Detrending with Hammett's equation

 [chemspacelab/Enhanced-Hammett](https://github.com/chemspacelab/Enhanced-Hammett)



Geometries with Graph2Structure

 [qmlcode/qml](https://github.com/qmlcode/qml)



Estimate computational cost

 [ferchault/mlscheduling](https://github.com/ferchault/mlscheduling)

Idea

- Molecular representation for each molecule i
 - CM, BoB, FCHL, SLATM, ...
- Distance metric
 - Typically L1 or L2 norm
- Kernel function
 - Laplacian, Gaussian

$$\mathbf{M}_i$$

$$d_{ij} \equiv d(\mathbf{M}_i, \mathbf{M}_j)$$

$$k_{ij} \equiv k(d_{ij})$$

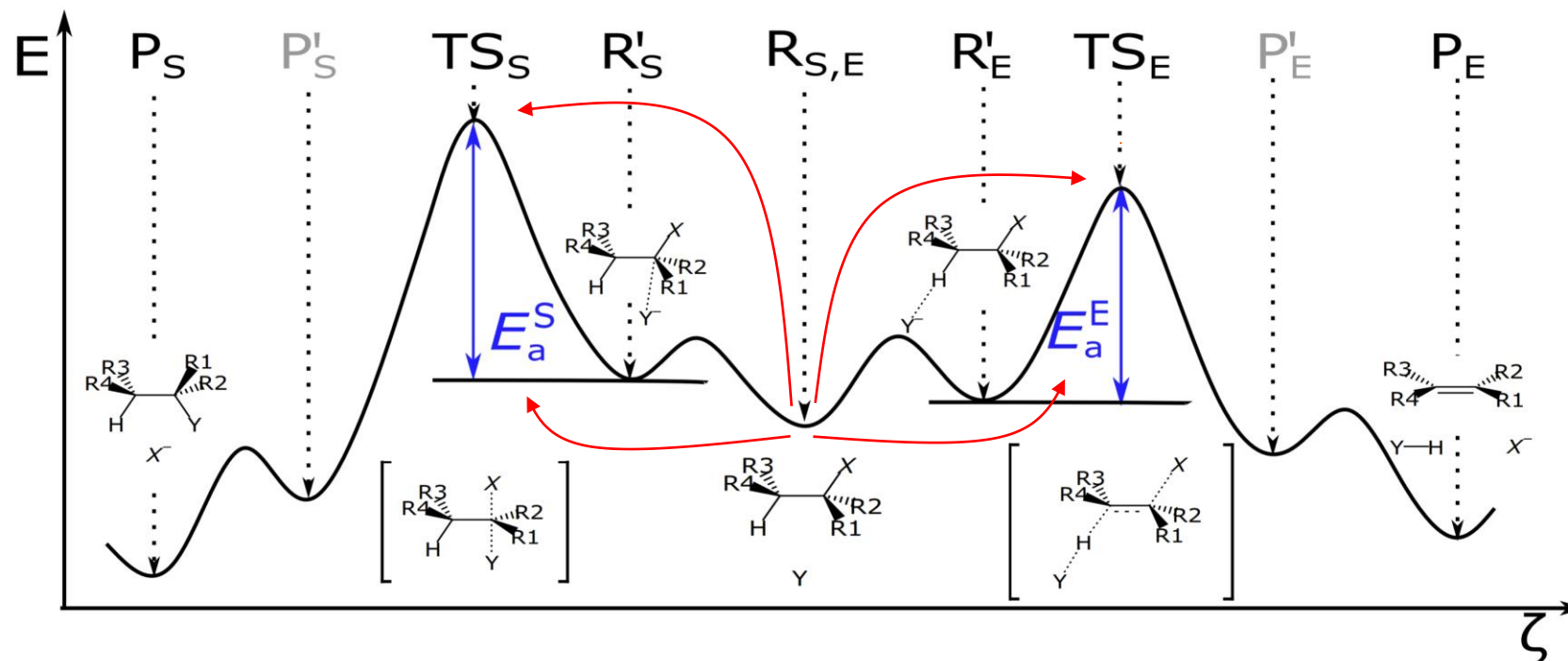
Procedure

- Get i data points with scalar property (label) $\{q_i\}$
 - E.g. atomisation energy
- Calculate all representations $\{\mathbf{M}_i\}$
 - typically ~1k
- Find distance and kernel matrices \mathbf{D}, \mathbf{K}
 - Symmetric
- Train model for predictions $\{\tilde{q}_i\}$
- Find best hyperparameters (cross-validation)

$$\arg \min_{\alpha} \sum_i (q_i - \tilde{q}_i)^2 + \lambda \sum_{ij} \alpha_i \alpha_j k_{ij}$$

$$\Rightarrow \alpha = (\mathbf{K} + \lambda \mathbf{I})^{-1} q \qquad \tilde{q}(\mathbf{M}) = \sum_i \alpha_i k(\mathbf{M}, \mathbf{M}_i)$$

Competing Reactions: E2 and S_N2



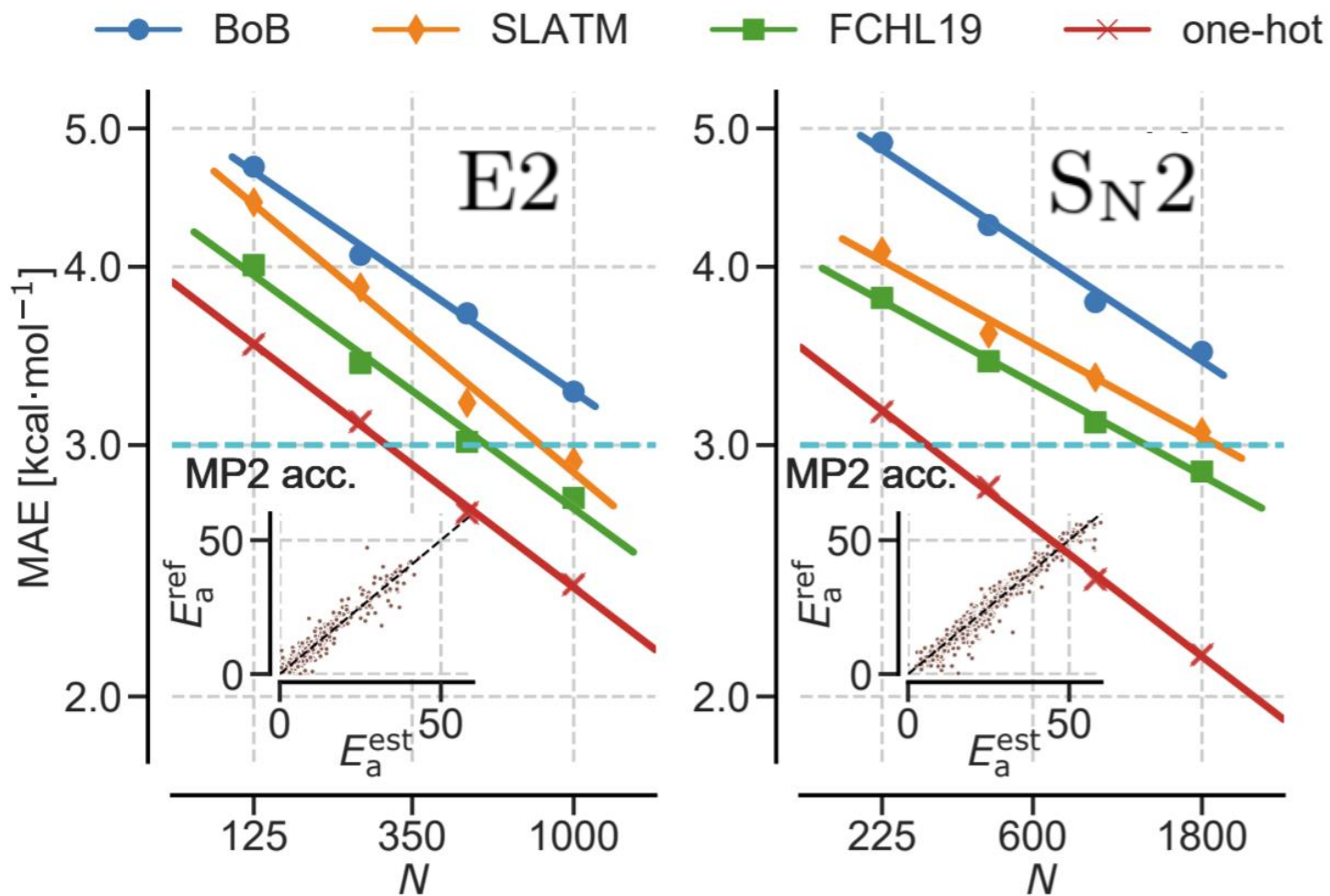
R	X	Y
H	F	H
NO ₂	Cl	F
CN	Br	Cl
CH ₃		Br
NH ₂		

- Activation energies E_a
- Transition state geometries
- Dataset of 4.5k transition states, 143k reactant geometries, part MP2, part DF-LCCSD

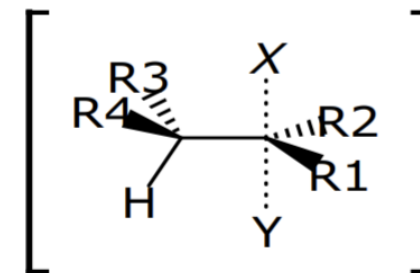
GFvR, S. Heinen, M. Bragato, O. A. von Lilienfeld, *Mach. Learn.: Sci. Technol.* 2020 (arXiv 2006.00504).

Learning Activation Energies

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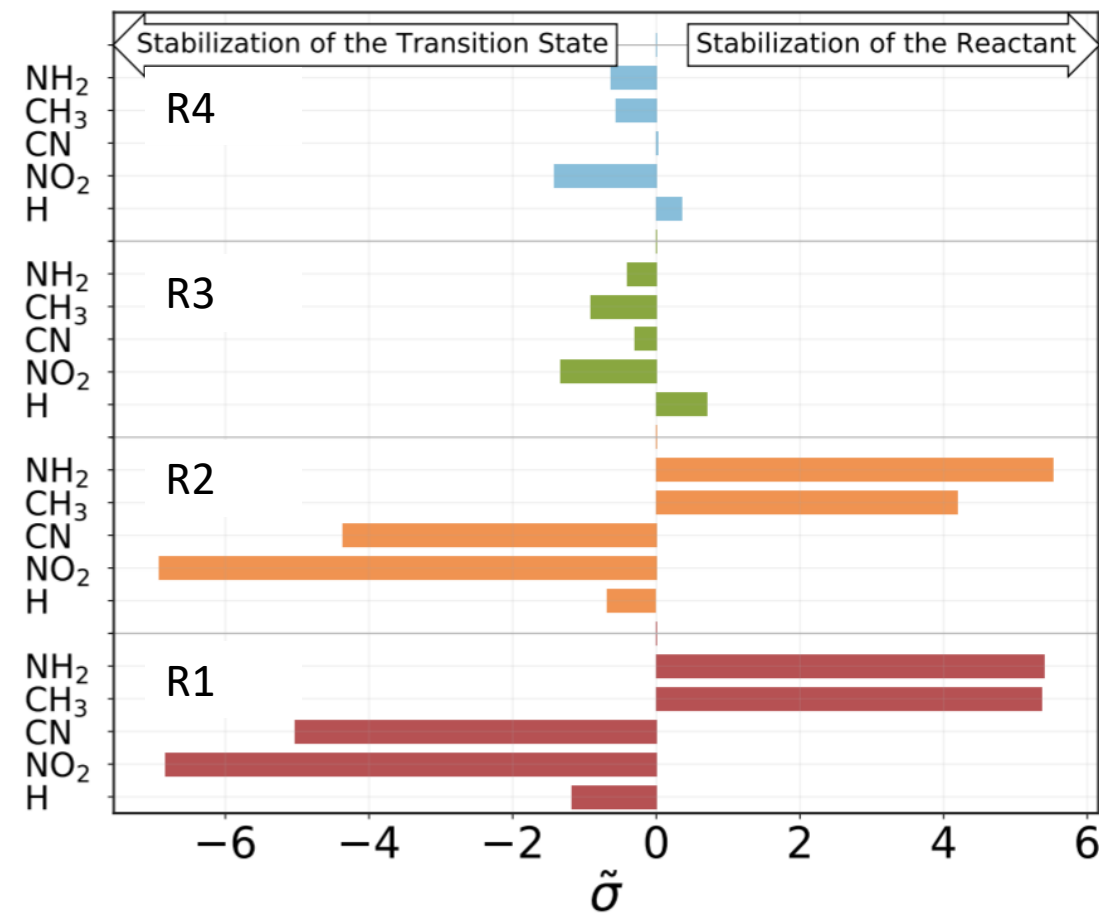
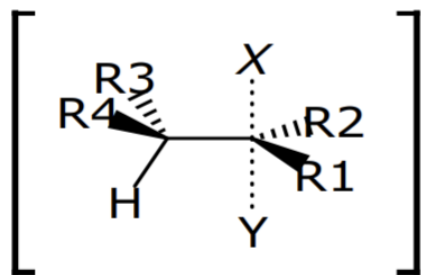


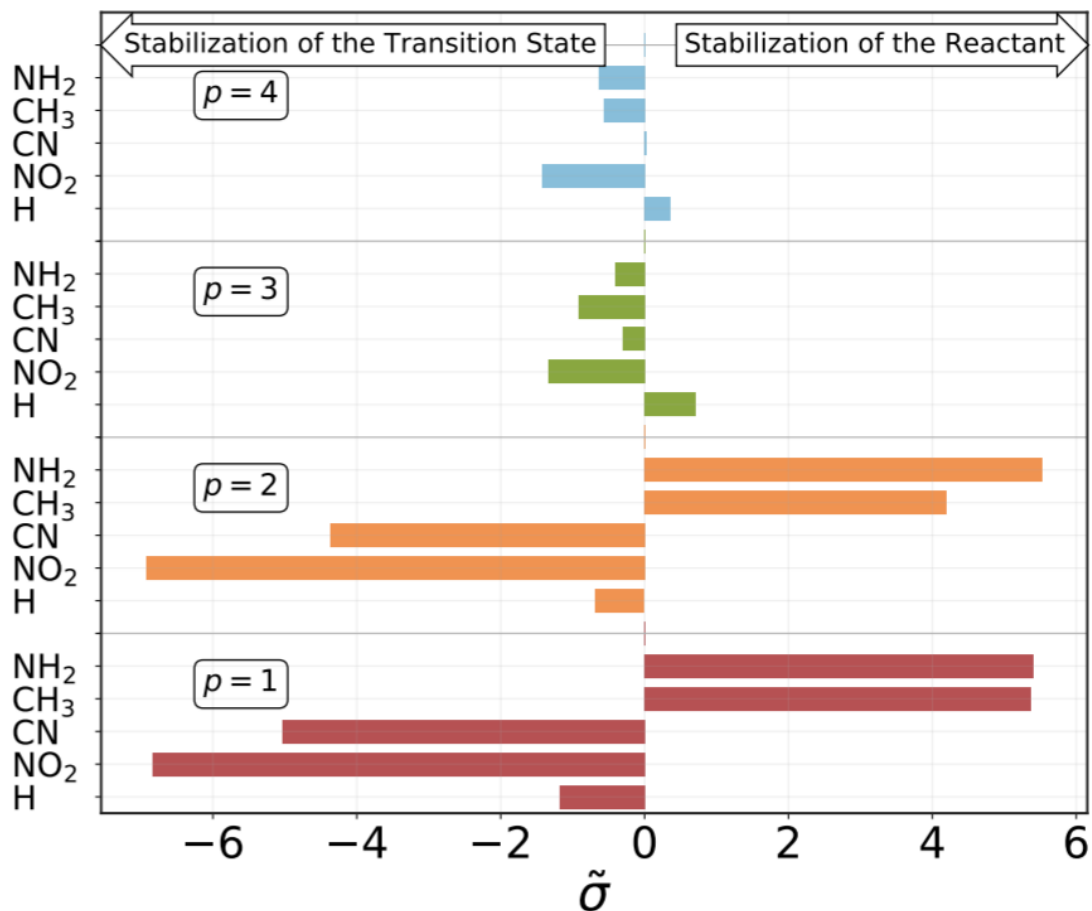
- Geometry-based representations on lowest conformer
 - BoB
 - SLATM
 - FCHL19
- Graph-based representations
 - One-hot



Learning Activation Energies

- Often in chemistry: trends obscure relevant detail
 - Electron density dominated by individual atoms
 - Energies dominated by elemental composition
 - Bond energies dominated by element pairs
- ...



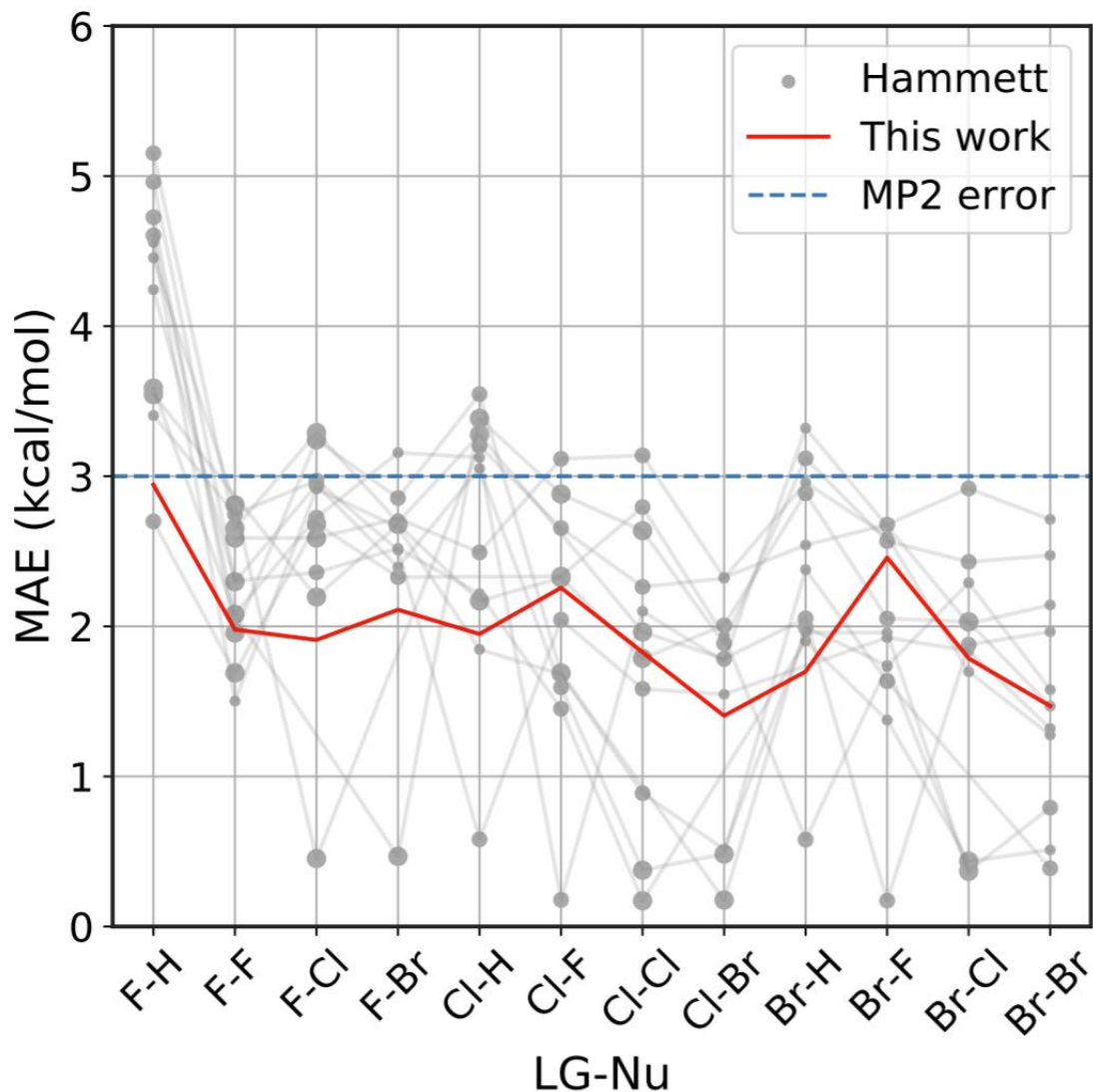


Hammett's equation (1935):

$$\log \left(\frac{K}{K_0} \right) \simeq \rho \sigma$$

Can be used to remove linear trends in the data

1. Find two aspects (e.g. solute/solvent) that are orthogonal and approximately balanced in the data set
2. Fit rho, sigma in a robust manner

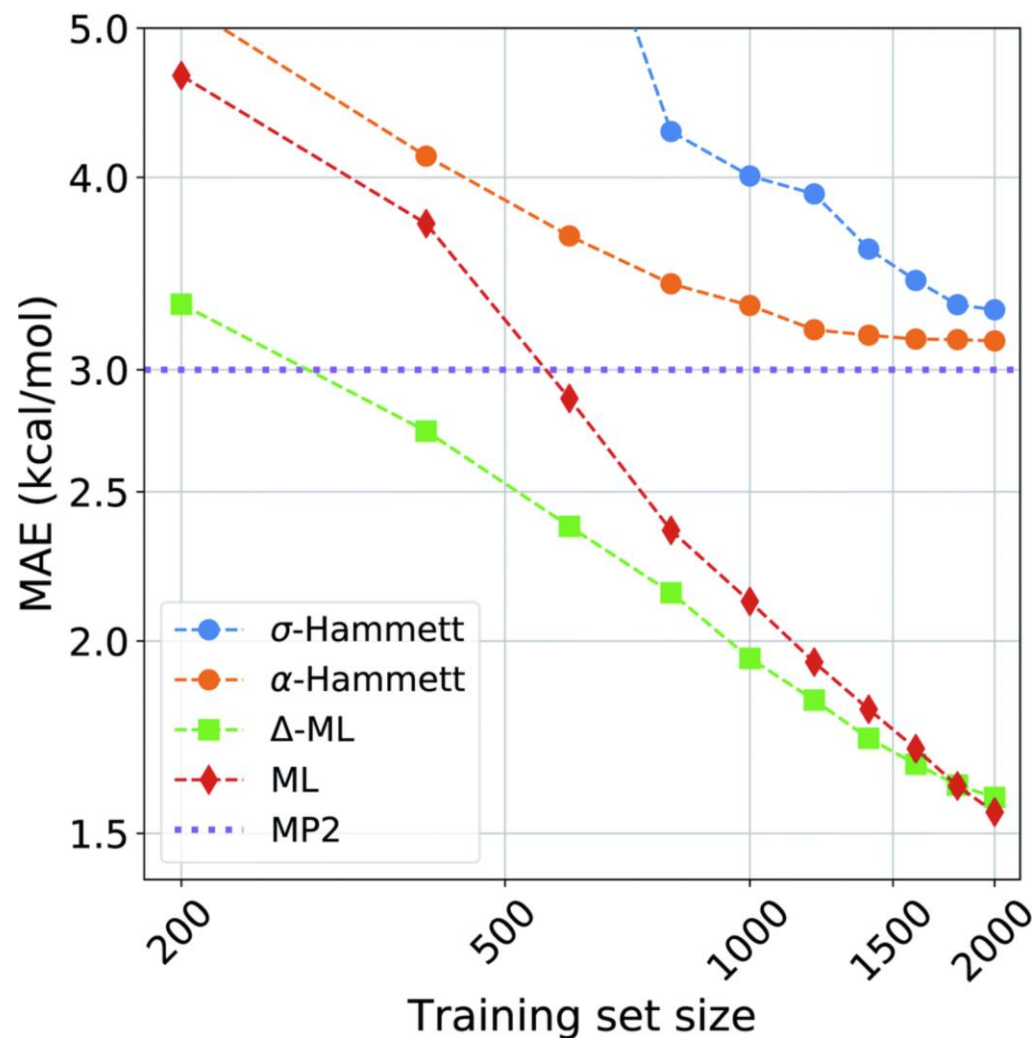


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- Hammett nearly reaches MP2 accuracy
- Residuals are easier to learn
- Preprocessing of datasets most helpful for small training sets

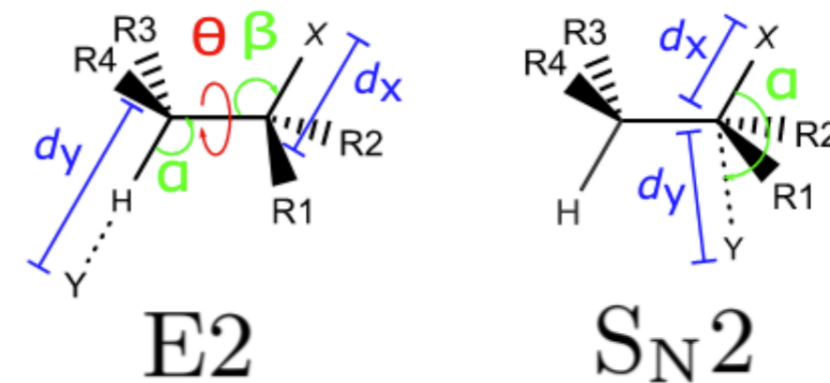
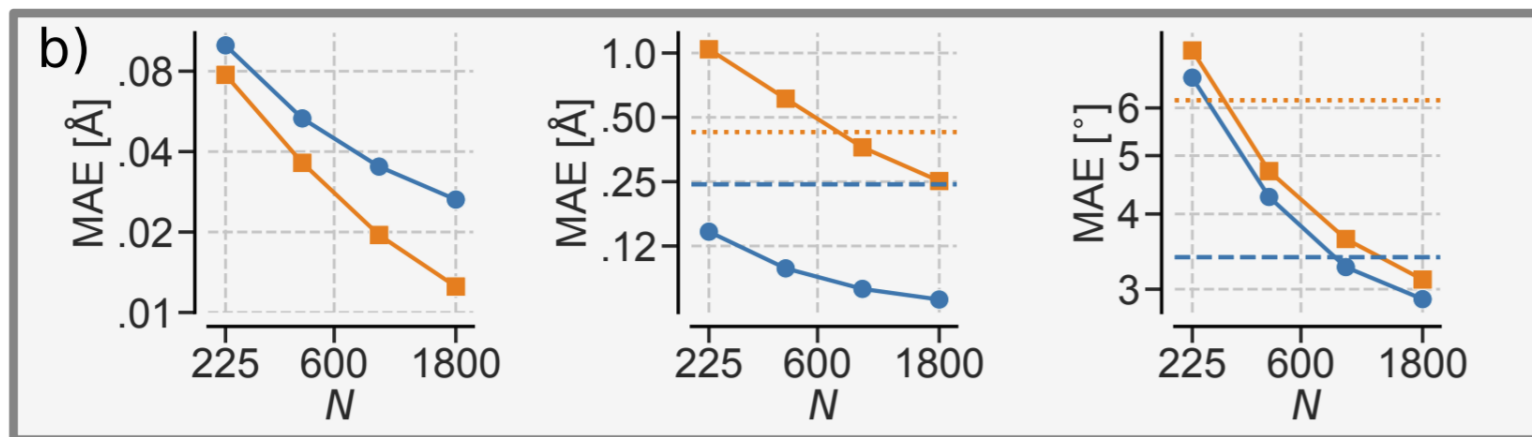
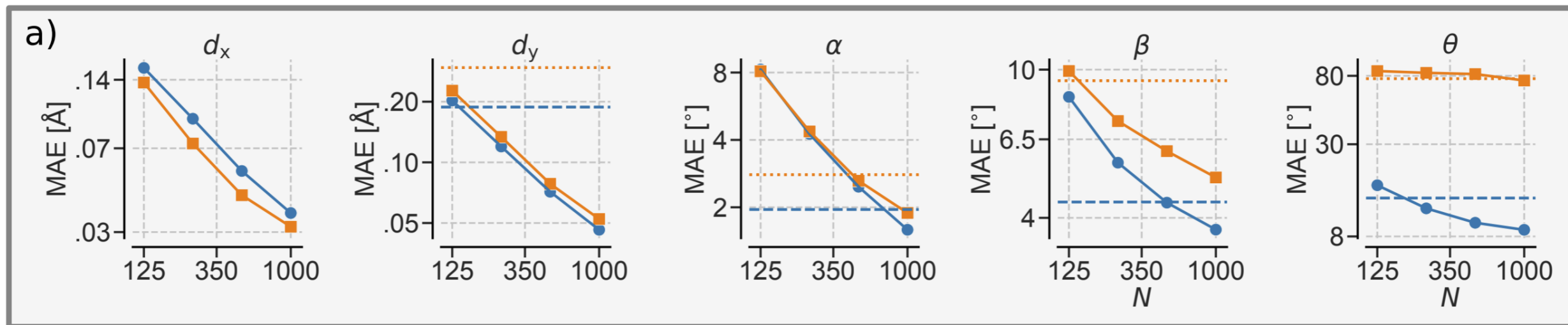


chemspacelab/Enhanced-Hammett

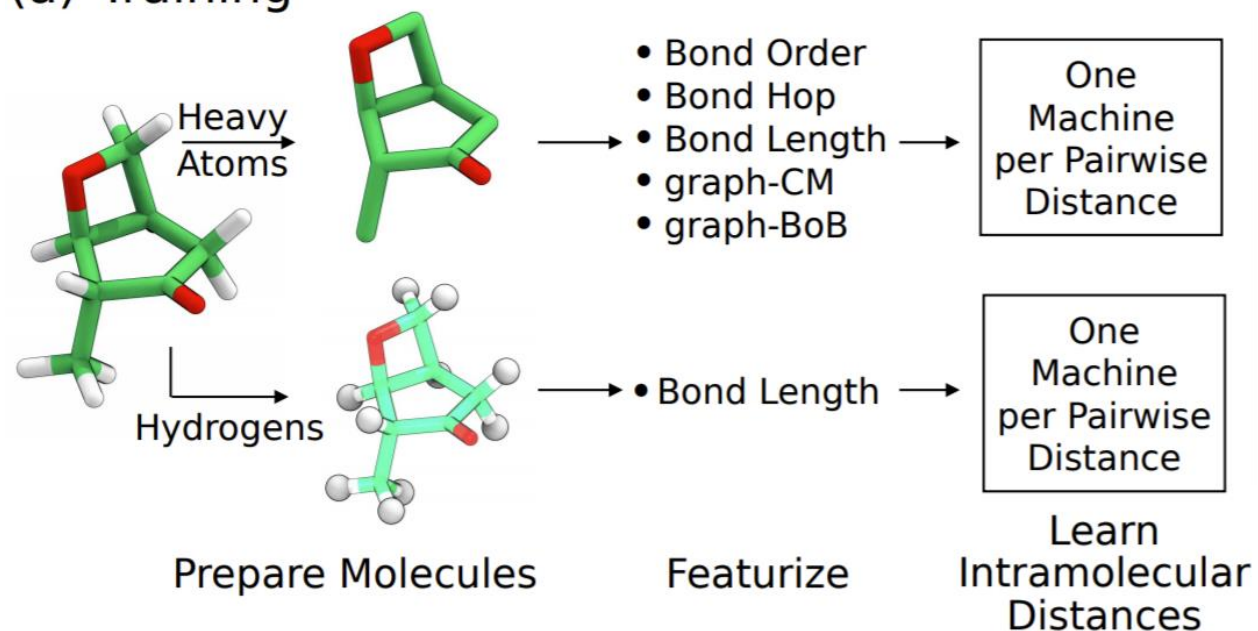
Learning Transition State Geometries

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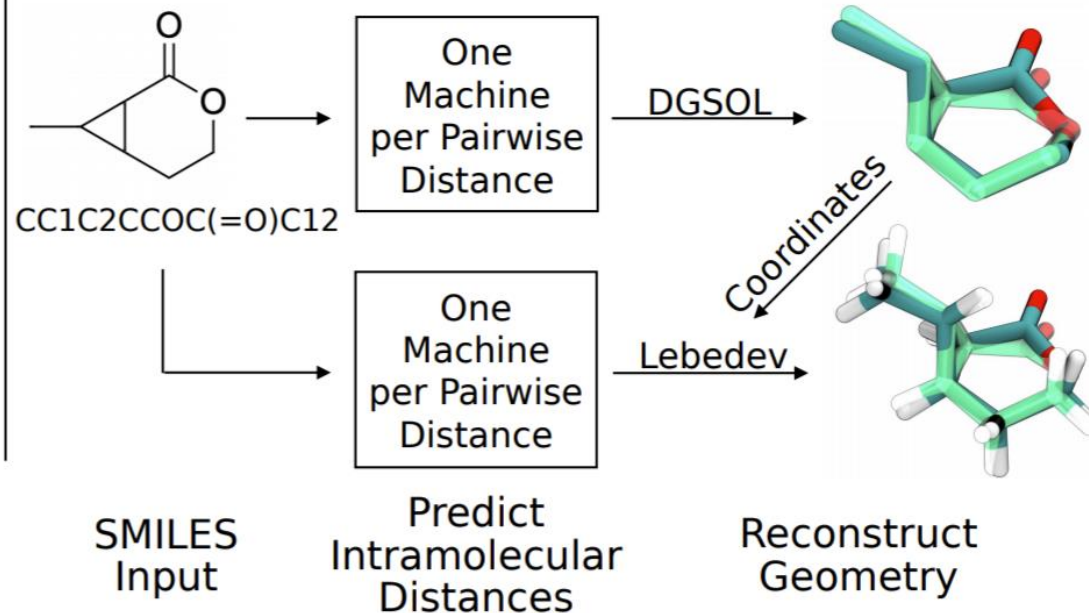
—●— Transition state —■— Reactant complex

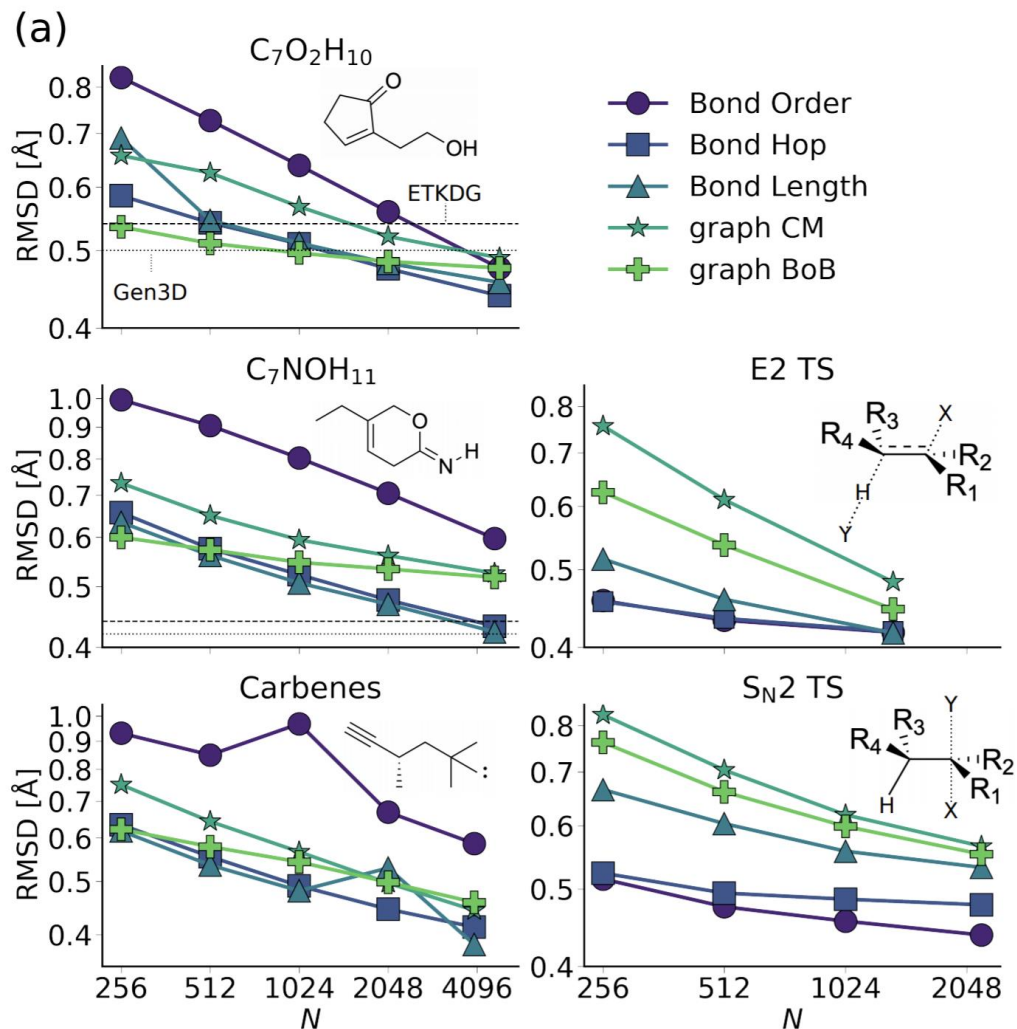


(a) Training

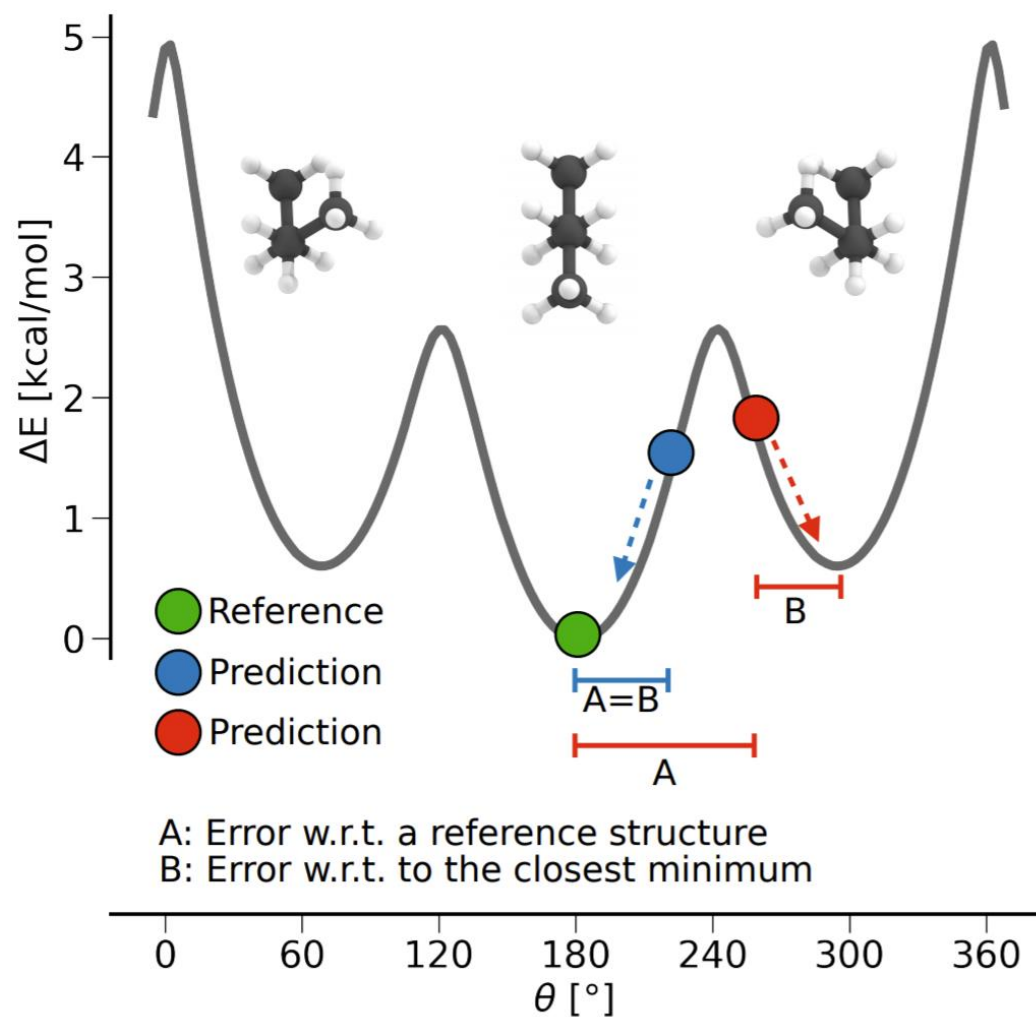


Prediction





- Learns standard chemistry, but also carbenes, transition state geometries
- More accurate w.r.t. to QM calculations than state-of-the-art embedding methods (which only do standard chemistry)
- Can produce initial guesses for e.g. transition state searches

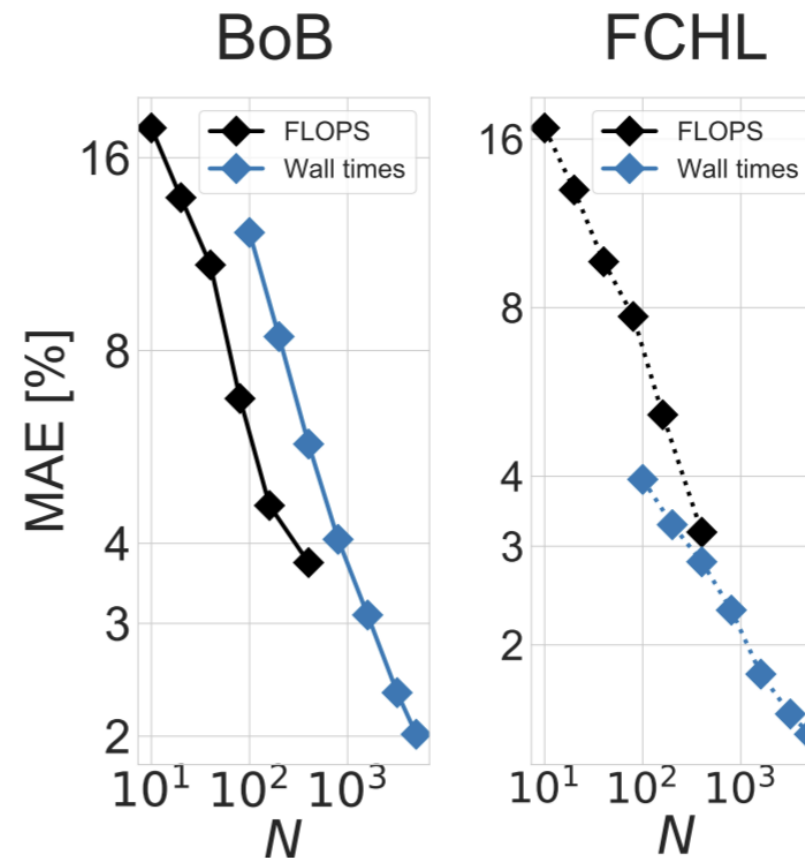


- Most efficient for cases with wide minima
- Multiple small minima e.g. stereoisomers account for most of the error

 qmlcode/qml

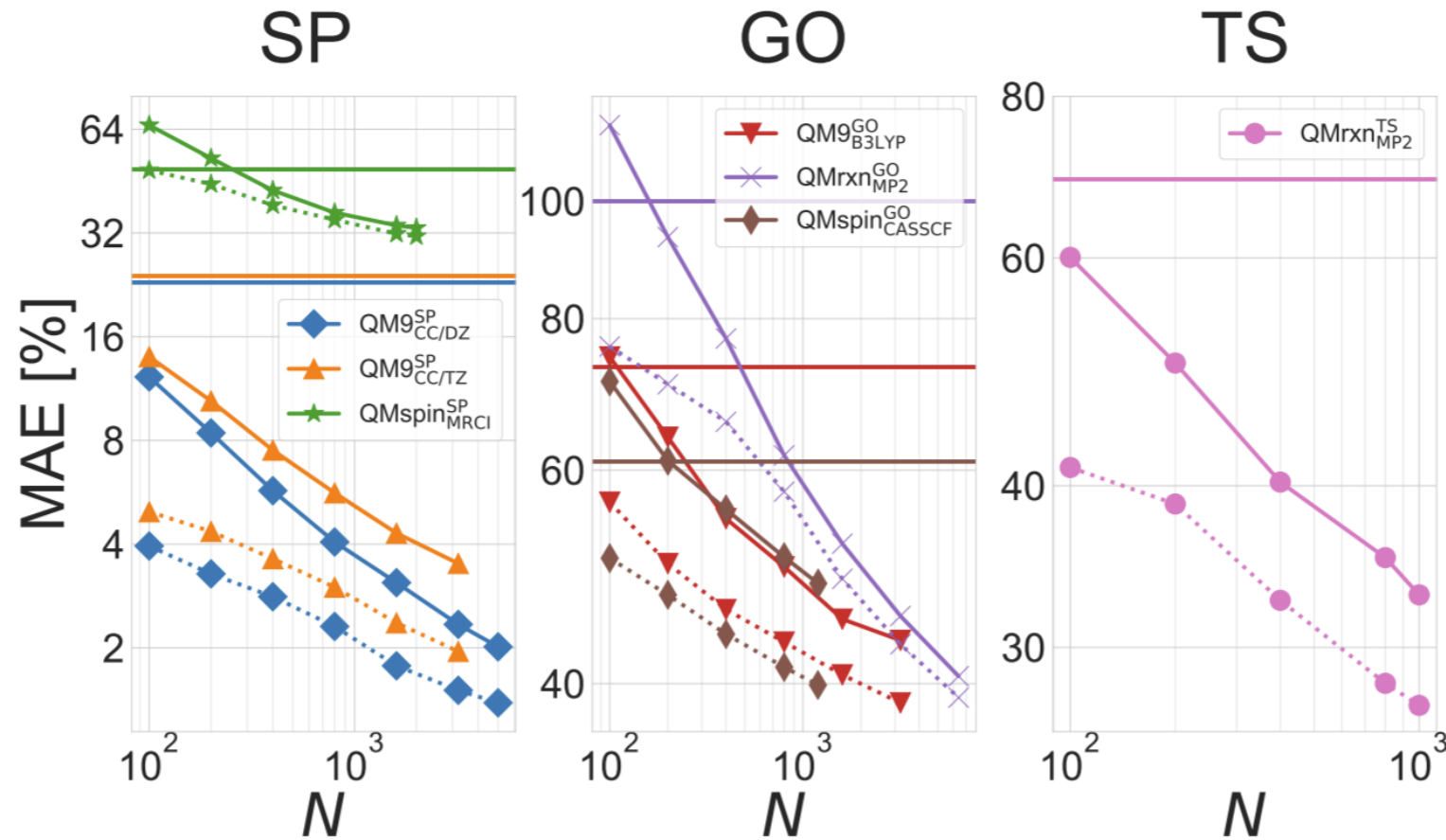
- Training data expensive
- Not all training points equally expensive
 - Geometry optimisations may take longer
 - SCF might not converge or converge more slow
- Treating this as “molecular property”

- Best case: controlled environment, single points (QM9)



Learning Computational Cost

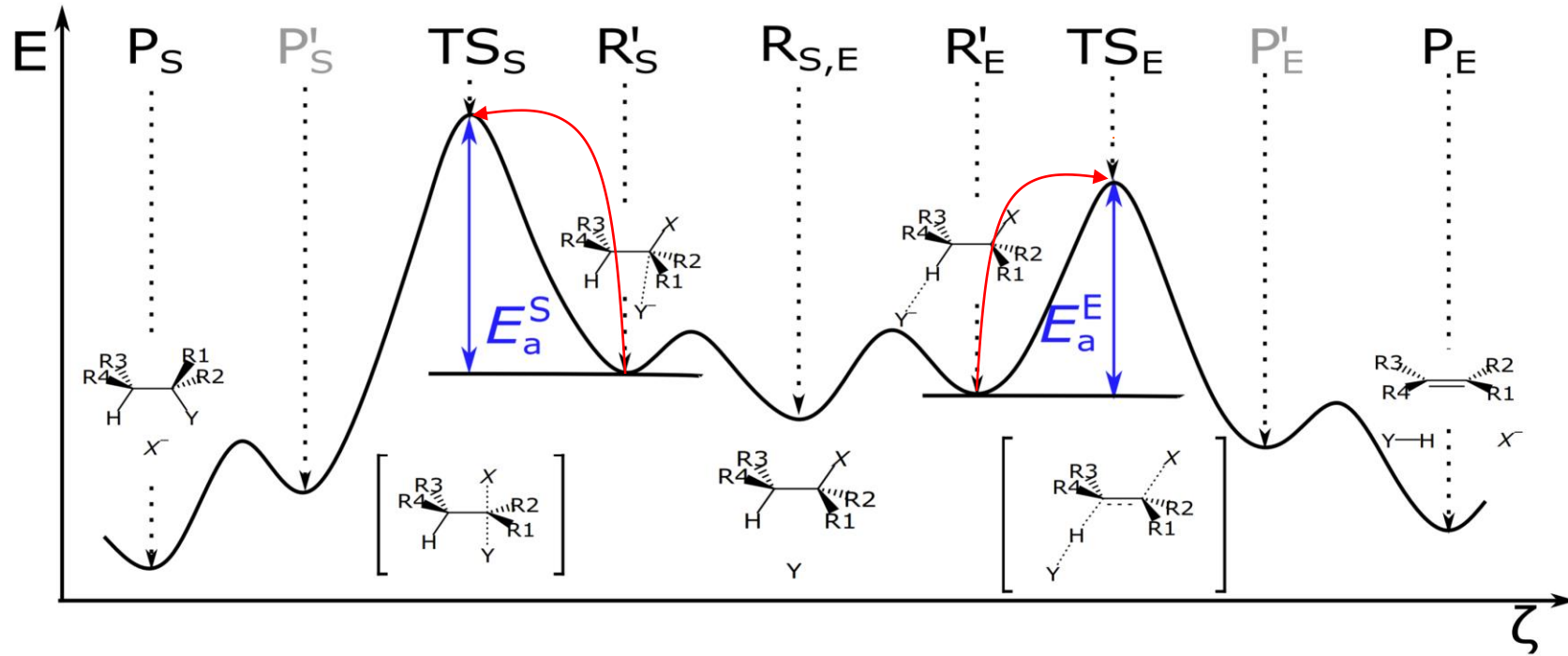
- Realistic case: I/O, noise: different machines



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What about direct optimization?

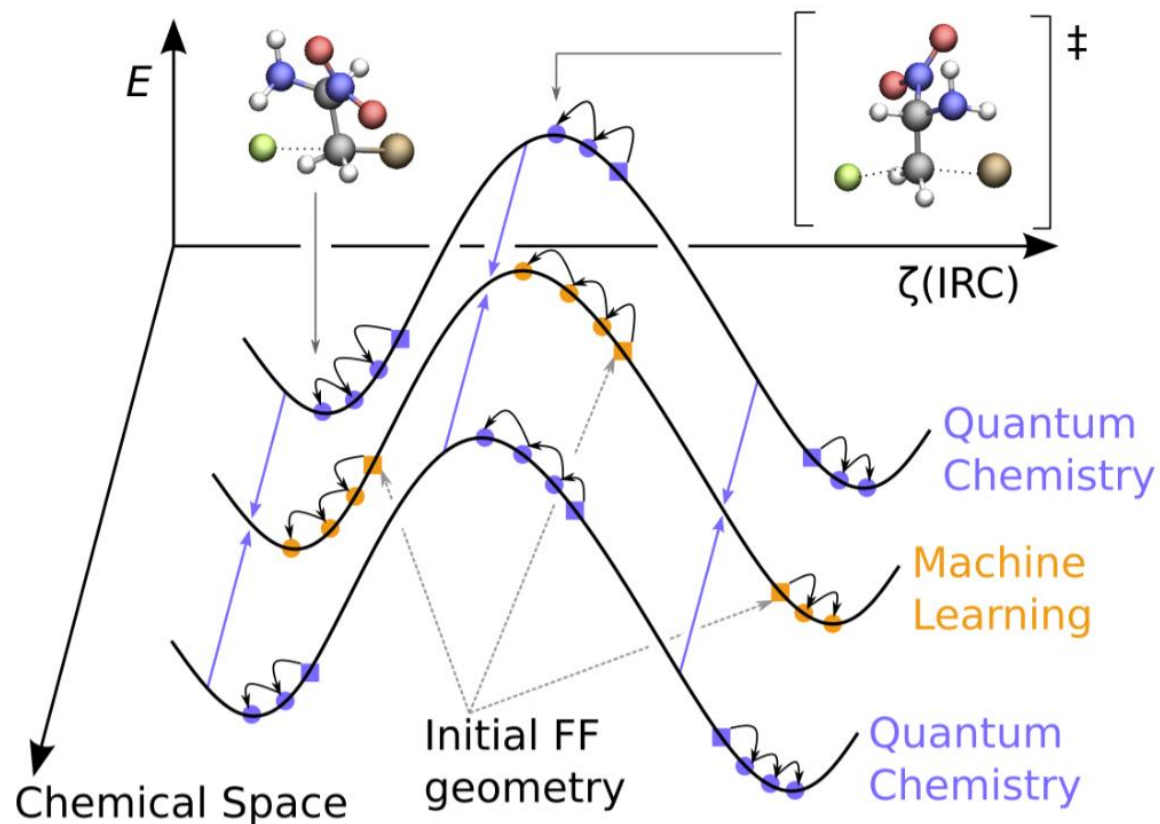
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S. Heinen, GFvR, O. A. von Lilienfeld, *in preparation*

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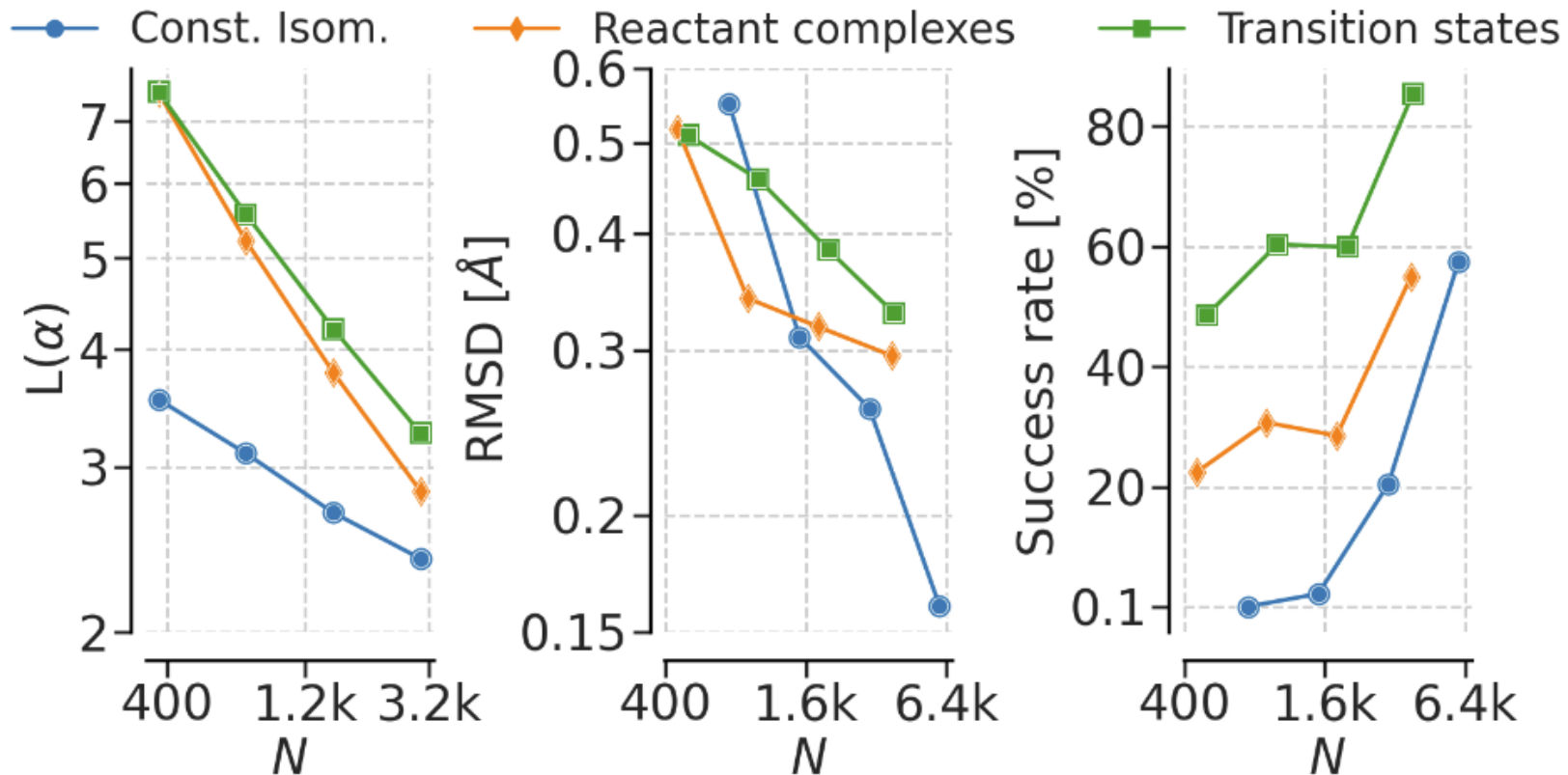
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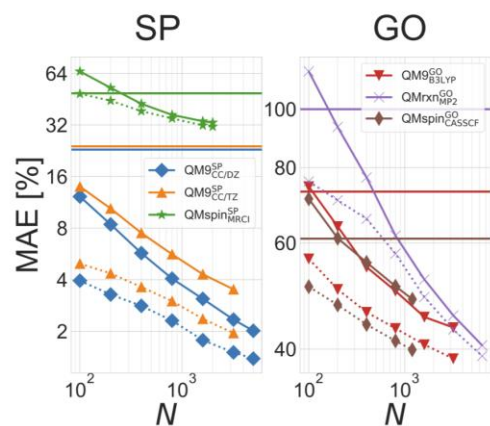


$$J(\alpha) = \left\| \begin{bmatrix} \mathbf{y} \\ \mathbf{f} \end{bmatrix} - \begin{bmatrix} \mathbf{K} \\ -\frac{\partial}{\partial \mathbf{r}} \mathbf{K} \end{bmatrix} \alpha \right\|_2^2$$

$$L(\alpha) = 0.01 \sum_i (y_i - y_i^{\text{est}})^2 + \sum_i \frac{1}{n_i} \|\mathbf{f}_i - \mathbf{f}_i^{\text{est}}\|^2$$

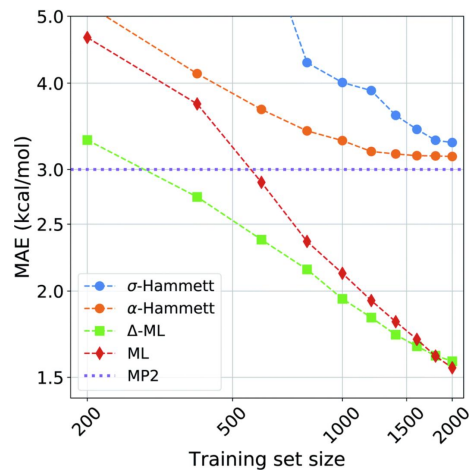
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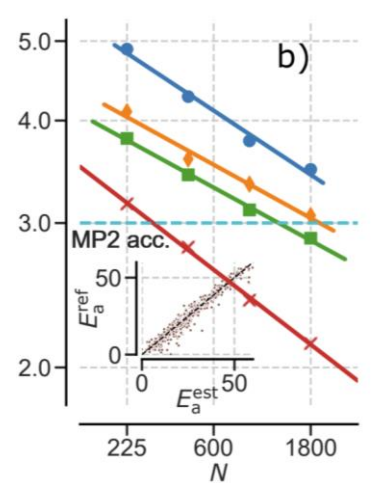
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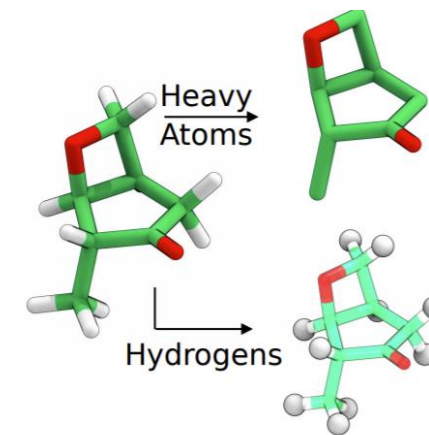
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